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If a control system include one or more nonlinear cha-racteristic element or link , the system is named as the nonlinear control system. 7.1.3 The typical nonlinearities $y(t)$ (1) Saturation nonlinearity b Mathematic al description $a k x(t)$ $kx(t)$ $x(t)$ a 0 $y(t)$ b ka sign $x(t)$ $x(t)$ a a linear zone width; k slope of the linear characteristic; 1 $x(t)$ 0 sign $x(t)$ 1 $x(t)$ 0 242 7.1.3 The typical nonlinearities Actual examples: saturation characteristic of the amplifier;valve ...

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